## Introduction to the Calculus of Variations Exercise sheet 1

Ex.1.1 (Properties of convex functions) Let $f: C^{2}\left(\mathbb{R}^{n}\right) \rightarrow \mathbb{R}$, show that the following assertions are equivalent.

1. For all $x, y \in \mathbb{R}^{n}$ and $0 \leq \lambda \leq 1$,

$$
f(\lambda x+(1-\lambda) y) \leq \lambda f(x)+(1-\lambda) f(y)
$$

2. For all $x, y \in \mathbb{R}^{n}$,

$$
f(x) \geq f(y)+\langle\nabla f(y), x-y\rangle .
$$

3. For all $x, y \in \mathbb{R}^{n}$,

$$
\langle\nabla f(x)-\nabla f(y), x-y\rangle \geq 0
$$

4. For all $x, v \in \mathbb{R}^{n}$,

$$
\left\langle\nabla^{2} f(x) v, v\right\rangle \geq 0
$$

Ex.1.2 (Implicit function theorem)
Let $f: \mathbb{R}^{2} \rightarrow \mathbb{R}, C^{1}$ and such that $f(0,0)=0$ and $\partial_{y} f(0,0) \neq 0$. We want to prove that there exist $\varepsilon>0$ and a $C^{1}$ function $\left.\varphi:\right]-\varepsilon, \varepsilon[\rightarrow]-\varepsilon, \varepsilon[$ such that for all $x, y \in]-\varepsilon, \varepsilon[$

$$
f(x, y)=0 \Longleftrightarrow y=\varphi(x)
$$

Without loss of generality, we assume $\partial_{y} f(0,0)>0$.

1. Show that there exists $\varepsilon>0$, such that for all $x \in[-\varepsilon, \varepsilon],[-\varepsilon, \varepsilon] \ni y \mapsto f(x, y)$ is strictly increasing.
2. Deduce that for all $x \in[-\varepsilon, \varepsilon]$, there exists a unique $\varphi(x) \in[-\varepsilon, \varepsilon]$ such that $f(x, y)=0$ if and only if $y=\varphi(x)$.
3. Using a Taylor expansion of $f$ around $(0,0)$, show that $\varphi$ is differentiable at 0 .
4. Show that it is in fact differentiable on $]-\varepsilon, \varepsilon\left[\right.$ and $C^{1}$ on this set.

Ex.1.3 (Weierstrass example)
Let $f(x, \xi)=x \xi^{2}$ for $x, \xi \in \mathbb{R}$ and consider, for $\varepsilon \in[0,1)$,

$$
\begin{aligned}
& \left(P_{\varepsilon}\right) \quad m_{\varepsilon}=\inf _{u \in X}\left\{I(u):=\int_{\varepsilon}^{1} f\left(x, u^{\prime}(x)\right) \mathrm{d} x\right\}, \\
& X_{\varepsilon}=\left\{u \in C^{1}([0,1]), \quad u(\varepsilon)=1, u(1)=0\right\} .
\end{aligned}
$$

1. Show that for $\varepsilon \in(0,1)$ there is a unique minimizer of $(P)$ in $C^{2} \cap X_{\varepsilon}$.
2. Show that for $\varepsilon=0$ there is no minimizer of $(P)$ in $X_{0} \cap C^{2}$.
3. Find a sequence $\left\{u_{n}\right\} \subset C_{p}^{1}$ (piecewise $C^{1}$ ) such that $u_{n}(0)=1, u_{n}(1)=0$ and $I\left(u_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$.
4. Show that $m_{0}=0$ and that there is therefore no minimizer of $(P)$ in $X$.

Ex.1.4 (Lagrange multipliers: finite dimensional case)
Let $n \geq 1, \Omega \subset \mathbb{R}^{n}$ open and $f, g: \Omega \rightarrow \mathbb{R}^{n} C^{1}$ functions. Assume that

- $f$ has a local minimum at $x_{0} \in \Omega$ subject to the condition $g(x)=0$, that is

$$
\exists \varepsilon>0, \quad\left|x-x_{0}\right| \leq \varepsilon \text { and } g(x)=0 \Longrightarrow f(x) \geq f\left(x_{0}\right)
$$

- $\nabla g\left(x_{0}\right) \neq 0$.

Show that there exists $\lambda \in \mathbb{R}$ such that

$$
\nabla f\left(x_{0}\right)=\lambda \nabla g\left(x_{0}\right)
$$

Hint: Adapt the proof of the theorem from the lecture with the isoperimetrical constraint.
Ex.1.5 (Lagrange multipliers: application) Let $A \in \mathcal{M}_{n}(\mathbb{R})$ be a non-negative matrix $A \geq 0$ (that is $\langle x, A x\rangle \geq 0$ for all $\left.x \in \mathbb{R}^{n}\right)$. Define

$$
\begin{aligned}
m & :=\inf _{x \in X}\{I(u)=\langle x, A x\rangle\} \\
X & =\left\{x \in \mathbb{R}^{n}, \text { such that }\|x\|=1\right\} .
\end{aligned}
$$

Using the implicit function theorem, prove that the minimization problem has a solution $x_{0}$ and that $x_{0}$ is en eigenvector of $A$ with eigenvalue $m$.

Ex.1.6 (Geodesics of the Euclidean space are straight lines)
Show that the geodesics (path of minimum distance between two points) of the Euclidean space are straight lines (at least among $C^{1}$ paths).

Hint: For a $C^{2}$ path $\gamma:[0,1] \rightarrow \mathbb{R}^{n}$, for some $n \geq 1$, defines the length of $\gamma, L(\gamma)$, and compute the Euler-Lagrange equation.

Ex.1.7 (Geodesics of the cylinder are helices)
Consider $\Sigma=\left\{(x, y, z) \in \mathbb{R}^{3},|z|=1\right\}$.

1. Show that the geodesics on $\Sigma$ are helices, that is they can be parametrized by $\gamma(t)=$ $(\cos (\omega t), \sin (\omega t), \alpha t+\beta)$ for some $\omega, \alpha, \beta \in \mathbb{R}$.

Hint: There are always many ways to parametrize a path, a smart way is to pick one parametrized by arclength, that is $\left|\gamma^{\prime}(s)\right|=1$ for all $s$.
2. What is the shortest path on $\Sigma$ from $(1,0,0)$ to $(1,0,1)$ ?

## Ex.1.8 (Lagrangian formalism)

Let $n \geq 1, V: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be $C^{2}$ and define $f(t, u, \xi)=\frac{1}{2} m \xi^{2}-V(u)$, for $u, \xi \in \mathbb{R}^{n}$. For some $X_{0}, X_{1} \in \mathbb{R}^{n}$, consider the minimization problem

$$
\begin{aligned}
& (P) \quad m=\inf _{u \in X}\left\{I(u):=\int_{0}^{1} f\left(t, u(t), u^{\prime}(t)\right) \mathrm{d} t\right\}, \\
& X=\left\{u \in C^{1}([0,1]), \quad u(0)=X_{0}, u(1)=X_{1}\right\} .
\end{aligned}
$$

Assume that $u_{0}:[0,1] \rightarrow \mathbb{R}^{n}$ is $C^{2}$ and solves the above minimization problem.

1. Show that the energy $H(u, \xi)=\frac{1}{2} m \xi^{2}+V(u)$ is preserved along the trajectory $u_{0}$.
2. Show that $u_{0}$ satisfies Newton's principle, that is

$$
m u^{\prime \prime}=F(u)
$$

where $F: \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ is a function to be determined in terms of $V$.
In this setting $f$ is called the Lagrangian of the system and I the action. The formalism of Lagrange is, to some extent, equivalent to the ones of Newton and Hamilton.

## Ex.1.9 (Fermat's principle)

A light beam goes from $(0,1) \in \mathbb{R}^{2}$ to $(1,-1) \in \mathbb{R}^{2}$. In the upper half plane $\{y>0\}$, the speed of light is $c / n_{1}$ and $c / n_{2}$ in the lower half plane $\{y<0\}$, for some indices $n_{1}, n_{2} \geq 1$. The trajectory of light follows the path of shortest time. Show that when it crosses the plane $\{y=0\}$, we have $n_{1} \sin \theta_{1}=n_{2} \sin \theta_{2}$ where we have denoted by $\theta_{1}$ and $\theta_{2}$ the angles of incidence.

