

# Chapter 1: Laplace / Poisson equation

$$-\Delta u = 0$$

Laplace

or

$$-\Delta u = f$$

Poisson

Def. let  $\Omega$  open  $\subset \mathbb{R}^d$ , any  $u \in C^2(\Omega)$   
and  $\Delta u = 0$  on  $\Omega$  is a harmonic function  
on  $\Omega$

## Relation to complex analysis.

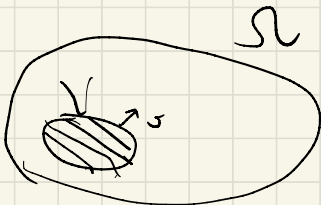
$u: \mathbb{C} \rightarrow \mathbb{C}$  analytic function

$$\rightarrow (\partial_{xx} + \partial_{yy}) \operatorname{Re} u = 0$$

or  $\operatorname{Im} u$  (Tutorial)

$$(\mathbb{C} \simeq \mathbb{R}^2)$$

## Physical interpretation: $\Omega \subset \mathbb{R}^d$



$u =$  density

In equilibrium,  $\forall V \subset \Omega$

(Exercise) Gauss-Green

$$\int_{\partial V} F \cdot \vec{\nu} \, ds = 0 \quad (\text{flux of } u \text{ through } V=0)$$
$$\int_V \operatorname{div}(F) \, dx \quad \hookrightarrow \quad F = -a \nabla u, \quad a > 0$$

$$\Rightarrow \int_V (\Delta u)(x) dx = 0, \quad \forall V \subset \Omega$$

open

$\Rightarrow \Delta u(x) = 0$  (Fundamental theorem  
Calculus of variations)  
 $\downarrow$   
(Exercise)

Exercise (Gauss - Green formula)

$$\int_{\partial V} F \cdot \vec{\nu} dS = \int_V \operatorname{div}(F)(x) dx$$

$V$  open  $\subset \mathbb{R}^d$

Exercise. If  $u \in C(\Omega)$  and

$$\int_V u(x) dx = 0, \quad \forall V \text{ open ball in } \Omega$$

$\Rightarrow u = 0$  almost everywhere.

Remark: The result holds also if  $u \in L^1(\Omega)$ .

Can you prove that?

Fundamental solution of Laplace equation:

$$\Delta u = 0 \text{ on } \mathbb{R}^d$$

Assume that  $u$  is radial:  $u(x) = v(r)$

with  $r = |x| = \sqrt{x_1^2 + \dots + x_d^2}$ . Then:

$$\frac{\partial r}{\partial x_i} = \frac{x_i}{r}$$

$$\partial_{x_i} u = v'(r) \frac{x_i}{r}$$

$$\partial_{x_i}^2 u = v''(r) \frac{x_i^2}{r^2} + v'(r) \left( \frac{1}{r} - \frac{x_i^2}{r^3} \right)$$

$$\Rightarrow \Delta u = v''(r) + \frac{d-1}{r} v'(r) = 0$$

$$\Rightarrow \log (v')' = \frac{v''}{v'} = \frac{d-1}{r}$$

$$\Rightarrow v' = \frac{\text{const}}{r^{d-1}}$$

$$\Rightarrow v = \begin{cases} \text{const} \log r + \text{const} & (d=2) \\ \text{const} \frac{1}{r^{d-2}} + \text{const} & (d=3) \end{cases}$$

Def. Fundamental solution of Laplace equation

$$\Phi(x) = \begin{cases} -\frac{1}{2\pi} \log|x| & d=2 \\ \frac{1}{4\pi|x|} & (d=3) \\ \frac{1}{d(d-2) \omega_{d-1} |x|^{d-2}} & (d \geq 3) \end{cases}$$

Remark: The fundamental solution  $\Phi$  is radial and satisfies

$$\Delta \Phi(x) = 0, \quad \forall x \in \mathbb{R}^d, \quad x \neq 0$$

$$|\nabla \Phi(x)| \in \frac{C}{|x|^{d-1}}, \quad |\Delta^2 \Phi(x)| \in \frac{C}{|x|^d}, \quad \forall x \neq 0$$

Remark: We do not have  $\Delta \Phi = 0$  on the whole  $\mathbb{R}^d$ . Indeed, we will see that

$$-\Delta \Phi(x) = \delta_0(x) \rightsquigarrow \text{Dirac-delta function}$$

formally  $\delta_0(x) = \begin{cases} 0 & y \neq 0 \\ \infty & y = 0 \end{cases} \quad \& \quad \int_{\mathbb{R}^d} \delta_0 = 1$

$\rightsquigarrow$  this will make sense in distribution theory (we discuss later)

Poisson equation:

$$-\Delta u(x) = f(x) \text{ on } \mathbb{R}^d$$

Solution: Let  $\Phi$  be the fundamental solution of Laplace equation. The solution of  $-\Delta u = f$  is

$$u(x) = (\Phi * f)(x) = \int_{\mathbb{R}^d} \Phi(x-y) f(y) dy$$

Theorem: If  $f \in C_c^2(\mathbb{R}^d)$ , then  $u \in C^2(\mathbb{R}^d)$  and  $\Delta u = f$  in  $\mathbb{R}^d$ .

Proof: We use the definition:

$$u(x) = \int_{\mathbb{R}^d} \Phi(x-y) f(y) dy = \int_{\mathbb{R}^d} \Phi(y) f(x-y) dy$$

Check:  $u$  is continuous. Take  $x_n \rightarrow x$

$\rightarrow u(x_n) \rightarrow u(x)$  by Dominated c.v.

[Recall measure theory, Monotone / Dominated c.v. theorem, ...]

Compute the derivatives:

$$\frac{u(x+he_i) - u(x)}{h} = \int \bar{\Phi}(y) \frac{f(x+he_i-y) - f(x-y)}{h} dy$$

$$\xrightarrow{h \rightarrow 0} \int \bar{\Phi}(y) \frac{\partial f}{\partial x_i}(x) dy$$

(Dominated c.v. again)

Similarly

$$D^\alpha u(x) = \int \bar{\Phi}(y) (D^\alpha f)(x-y) dy$$

$\in$  Continuous!  $\forall |\alpha| \leq 2$

Thus  $u \in C^2(\mathbb{R}^d)$  since  $f \in C_c^2(\mathbb{R}^d)$ .

Why  $\Delta u = f$ ?

$$-\Delta_x u = \int_{\mathbb{R}^d} \bar{\Phi}(y) (-\Delta_x) f(x-y) dy$$

$$= \int_{\mathbb{R}^d} \bar{\Phi}(y) (-\Delta_y) f(x-y) dy = \int_{\mathbb{R}^d \setminus B(0, \varepsilon)} + \int_{B(0, \varepsilon)}$$

The main part:

$$\int_{\mathbb{R}^d \setminus B(0, \varepsilon)} \Phi(y) (-\Delta_y) f(x-y) dy$$

$$= \int_{\mathbb{R}^d \setminus B(0, \varepsilon)} \bar{\Phi}(y) (-\Delta_y) f(x-y) dy$$

$$= \int_{\mathbb{R}^d \setminus B(0, \varepsilon)} (\nabla_y \Phi)(y) (\nabla_y f)(x-y) dy$$

$$- \int_{\partial B(0, \varepsilon)} \Phi(y) \frac{\partial f(x-y)}{\partial \vec{n}} dS(y)$$

$$= \int_{\mathbb{R}^d \setminus B(0, \varepsilon)} \overbrace{(-\Delta \Phi)(y)}^{=0} f(x-y) dy$$

$$\frac{\partial}{\partial \vec{n}} = \nabla \cdot \vec{n} \rightarrow \vec{n}$$

$$+ \int_{\partial B(0, \varepsilon)} \frac{\partial \Phi}{\partial \vec{n}}(y) f(x-y) dS(y)$$

$$- \int_{\partial B(0, \varepsilon)} \bar{\Phi}(y) \frac{\partial f}{\partial \vec{n}}(x-y) dS(y)$$

Direct computation:

$$\begin{cases} \nabla \Phi = - \frac{1}{d |B_1|} \cdot \frac{y}{|y|^d} \\ \vec{n} = - \frac{y}{|y|} \quad \text{on } \partial B(0, \varepsilon) \end{cases}$$

$$\Rightarrow \frac{\partial \Phi}{\partial \vec{n}} = \frac{1}{d |B_1| \varepsilon^{n-1}} \quad \text{on } \partial B(0, \varepsilon)$$

$$\Rightarrow \int_{\partial B(0, \varepsilon)} \frac{\partial \Phi(y)}{\partial \vec{n}} f(x-y) dS(y)$$

$$= \int_{\partial B(0, \varepsilon)} \frac{1}{d |B_1| \varepsilon^{n-1}} f(x-y) dS(y)$$

$$= \int_{\partial B(0, \varepsilon)} f(x-y) dS(y) \xrightarrow{\varepsilon \rightarrow 0} f(x)$$

mean value / average integral



On the other hand:

$$\left| \int_{\partial B(0, \varepsilon)} \Phi \frac{\partial f}{\partial \nu}(x-y) dS(y) \right|$$

$$\leq C \|\nabla f\|_{\infty} \int_{\partial B(0, \varepsilon)} |\Phi| \rightarrow 0 \text{ as } \varepsilon \rightarrow 0$$

Similarly:

$$\left| \Delta_x \int_{B(0, \varepsilon)} \Phi(y) f(x-y) \right|$$

$$= \left| \int_{B(0, \varepsilon)} \Phi \Delta_x f(x-y) \right|$$

$$\leq \|\Delta f\|_{L^{\infty}}$$

$$\int_{B(0, \varepsilon)} |\Phi| \rightarrow 0$$

$$C \varepsilon^{\frac{d-2}{2}} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0$$

Thus we conclude that

$$\Delta u(x) = f(x), \quad \forall x \in \mathbb{R}^d$$

$$\text{if } u = \Phi * f \text{ and } f \in C_c^2(\mathbb{R}^d).$$

## Harmonic functions in a domain $\Omega \subset \mathbb{R}^d$

Let  $\Omega$  open  $\subset \mathbb{R}^d$ . Let  $u \in C^2(\Omega)$  and

$$\Delta u = 0 \quad \text{in } \Omega.$$

Theorem: (Mean-value formula for harmonic function)

If  $u \in C^2(\Omega)$  and  $\Delta u = 0$  in  $\Omega$ , then:

$$u(x) = \int_B u = \int_{\partial B} u, \quad \forall \text{ ball } B \subset \Omega.$$

Proof: In 1D,  $\Delta u = 0 \rightarrow u$  is linear  $\rightarrow$  obvious.

In general case: consider

$$f(r) = \int_{\partial B(x,r)} u(y) dS(y) = \int_{\partial B(0,1)} u(x+rz) dS(z)$$

$$\rightarrow f'(r) = \int_{\partial B(0,1)} \nabla u(x+rz) \cdot z dS(z)$$

$$= \int_{\partial B(x,r)} \nabla u(y) \frac{y-x}{r} dS(y)$$

$$\dots = \int_{\partial B(x,r)} f \frac{\partial u}{\partial \vec{n}} dS(y)$$

Green's formula

$$= \frac{r}{d} \int_{B(x,r)} \Delta u(y) dy = 0$$

$$\Rightarrow f(r) = \text{const} \Rightarrow f(r) = \lim_{t \rightarrow 0} f(t) = u(x),$$

Consequently, by polar coordinates:

$$\int_{B(x,r)} u dy = \int_{B(0,r)} u(x+y) dy$$

$$= \int_0^r \left( \int_{\partial B(0,s)} u \right) ds$$

$$= \int_0^r |\partial B(0,s)| u(x) ds$$

$$= |B(0,r)| u(x) = |B(x,r)| u(x) \quad \square$$

Reverse  $\rightarrow$  exercise!!

Theorem (Maximum principle)  $\Omega$  open  $\subset \mathbb{R}^d$ .

Assume  $u \in C^1(\Omega) \cap C(\bar{\Omega})$ . Then:

$$a) \quad \max_{\bar{\Omega}} u = \max_{\partial\Omega} u$$

b) Assume  $\Omega$  is connected. If  $\exists x_0 \in \Omega$  s.t.  
 $u(x_0) = \max_{\bar{\Omega}} u$

Then  $u \equiv \text{const}$  in  $\Omega$ .

Proof: b) Assume  $\exists x_0 \in \Omega$  s.t.

$$u(x_0) = \max_{\bar{\Omega}} u.$$

Then  $\forall$  ball  $B$ :  $x_0 \in B \subset \Omega$  we have

$$u(x_0) = \int_B u(x) dx \leq \max_{\bar{\Omega}} u = u(x_0)$$

$$\Rightarrow u(x) = u(x_0), \forall x \in B$$

The set  $\{x : u(x) = u(x_0)\}$  is both open & closed within  $\Omega \rightarrow$  it is  $\Omega$  as  $\Omega$  is connected

(b)  $\Rightarrow$  (a)  $\checkmark$

Theorem (Uniqueness) let  $g \in C(\partial\Omega)$ ,  $f \in C(\Omega)$ .  
Then  $\exists$  at most one solution  $u \in C^2(\Omega) \cap C(\bar{\Omega})$

$$\text{to } \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

Proof. By linearity  $\leadsto f = g = 0$ .

$$\begin{cases} -\Delta u = 0 & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \Rightarrow u = 0 \text{ in } \Omega.$$

Exercise: Assume  $\Omega$  open, connected  $\subset \mathbb{R}^d$ .

let  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  s.t.

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases}$$

Prove that 1) if  $g \geq 0$ , then  $u \geq 0$  in  $\Omega$

2) if  $g \geq 0$  and  $g \not\equiv 0$ , then  
 $u > 0$  in  $\Omega$ .

Def: Let  $\Omega$  open  $\subset \mathbb{R}^d$  and  $u \in C^2(\Omega)$ .

- $u$  is subharmonic if  $\Delta u \geq 0$  in  $\Omega$
- $u$  is superharmonic if  $\Delta u \leq 0$  in  $\Omega$ .

Remark: In 1D, subharmonic = convex

Exercise: Let  $\Omega$  open  $\subset \mathbb{R}^d$  and  $u \in C^1(\Omega)$ ,  
 $\Delta u \geq 0$  (i.e.  $u$  is subharmonic).

(a) Prove the mean-value inequality

$$\int_{\partial B(x,r)} u(y) dS(y) \geq \int_{B(x,r)} u(y) dy \geq u(x)$$

for all  $x \in B(x,r) \subset \Omega$ .

(b) Assume that  $\Omega$  is connected and  $u \in C(\bar{\Omega})$ .

Prove the strong maximum principle, i.e. either

- $u = \text{const}$  in  $\Omega$ , or
- $\sup_{y \in \partial \Omega} u(y) > u(x)$  for all  $x \in \Omega$ .

Theorem: (Regularity) If  $u \in C(\Omega)$  and

$$u(x) = \int_B u, \quad \forall \text{ ball } B \subset \Omega.$$

Then  $u \in C^2(\Omega)$  and  $\Delta u = 0$ , i.e.  $u$  is harmonic.

Moreover,  $u \in C^\infty(\Omega)$  and  $u$  is analytic in  $\Omega$ .

Proof: Let  $\eta \in C_c^\infty(\mathbb{R}^d)$ , radial,  $\int \eta = 1$ ,

$$\eta_\varepsilon = \varepsilon^{-d} \eta\left(\frac{\cdot}{\varepsilon}\right) \quad \eta = 0 \text{ if } |x| \geq 1$$

$$u_\varepsilon = \eta_\varepsilon * u \in C^\infty(\Omega_\varepsilon)$$

where  $\Omega_\varepsilon = \{x \in \Omega : \text{dist}(x, \partial\Omega) > \varepsilon\}$ .

Then:

$$u_\varepsilon(x) = \int_\Omega \eta_\varepsilon(x-y) u(y) dy$$

$$= \frac{1}{\varepsilon^d} \int_{B(x, \varepsilon)} \eta\left(\frac{x-y}{\varepsilon}\right) u(y) dy$$

$$= \frac{1}{\varepsilon^d} \int_0^\varepsilon \eta\left(\frac{r}{\varepsilon}\right) \left( \int_{\partial B(x, r)} u dS \right) dr$$

$u(x) | \partial B(x, r) |$

$$= u(x) \int \eta_\varepsilon dy = u(x)$$

Since  $u_\varepsilon \in C^\infty(\Omega_\varepsilon) \Rightarrow u \in C^\infty(\Omega_\varepsilon), \forall \varepsilon$ .

To prove that  $u$  is analytic in  $\Omega$ , we need to show that  $\forall x_0 \in \Omega, \forall r > 0$  s.t.  $\forall x \in B(x_0, r)$

$$u(x) = u(x_0) + \sum_{\alpha \neq 0} c_\alpha (x - x_0)^\alpha$$

where  $y^\alpha = y_1^{\alpha_1} \dots y_d^{\alpha_d}$ ,  $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_d)$  and

series converge absolutely, i.e.

$$\sum_{\alpha} c_\alpha r^{|\alpha|} < \infty.$$

We know that  $u \in C^\infty(\Omega)$ . Hence,

by Taylor's expansion

$$u(x) = u(x_0) + \sum_{0 < |\alpha| < N} \frac{D^\alpha u(x_0)}{|\alpha|!} (x - x_0)^\alpha + R_N(x)$$

where  $|\alpha| = \alpha_1 + \dots + \alpha_d$ ,  $|\alpha| = \alpha_1 + \dots + \alpha_d$ , and

$$R_N(x) = \sum_{|\alpha| = N} \frac{D^\alpha u(x_0 + t(x - x_0)) (x - x_0)^\alpha}{|\alpha|!}$$

We need to prove that

$$|R_N(x)| \rightarrow 0 \quad \text{uniformly in } x \in B(x_0, r).$$



Lemma: (Estimates on derivatives) If  $u$  is harmonic in  $\Omega \subset \mathbb{R}^d$  and  $B(x_0, r) \subset \Omega$ , then  $\forall |d| = N$ ,

$$|D^d u(x_0)| \leq \frac{(C_d N)^N}{r^{d+N}} \int_{B(x_0, r)} |u|$$

where  $C_d$  depends only on  $d$ .

We will prove the Lemma later. Now we complete the proof of the analyticity.

For  $x_0 \in \Omega$ , let  $0 < r < \frac{1}{L+1} \text{dist}(x_0, \partial\Omega)$ .

Then  $\forall x \in B(x_0, r)$  we have

$$B(x, Lr) \subset B(x_0, (L+1)r) \subset \Omega$$

$$\begin{aligned} \stackrel{\text{Lemma}}{\Rightarrow} |D^d u(x)| &\leq \frac{(C_d N)^N}{(Lr)^{d+N}} \int_{B(x, Lr)} |u| \\ &\leq \left(\frac{C_d N}{Lr}\right)^N \underbrace{\frac{1}{(Lr)^d} \int_{B(x_0, (L+1)r)} |u|}_{\leq M} \end{aligned}$$

$$\Rightarrow \|D^d u\|_{C^\infty(B(x_0, r))} \leq M \left(\frac{C_d N}{Lr}\right)^N, \quad \forall |d| = N.$$

## Multinomial Theorem:

$$d^N = (1+1+\dots+1)^N = \sum_{|\alpha|=N} \frac{|\alpha|!}{\alpha!} = N! \sum_{|\alpha|=N} \frac{1}{\alpha!}$$

Stirling's formula: (exercise)

$$N! \sim \sqrt{2\pi N} \left(\frac{N}{e}\right)^N,$$

namely

$$\frac{N!}{\sqrt{2\pi N} \left(\frac{N}{e}\right)^N} \rightarrow 1 \text{ as } N \rightarrow \infty,$$

Thus:

$$\sum_{|\alpha|=N} \frac{\|D^\alpha u\|_{C^\infty(B(x_0, r))} r^{|\alpha|}}{\alpha!} \leq M \left(\frac{d C_d N}{L}\right)^N \frac{1}{N!}$$

$$\leq M \left(\frac{d C_d e}{L}\right)^N \rightarrow 0 \text{ as } N \rightarrow \infty$$

if we take  $L = L_d > d C_d e$ .

In conclusion, we get the series expansion:

$$u(x) = u(x_0) + \sum_{\alpha \neq 0} \frac{D^\alpha u(x_0)}{\alpha!} (x - x_0)^\alpha$$

for all  $x \in B(x_0, r)$ .

## Proof of the derivative bound:

For  $d=0$ , by the mean-value theorem

$$u(x_0) = \int_{B(x_0, r)} u(y) dy$$

$$\rightarrow |u(x_0)| \leq \frac{1}{|B_1| r^d} \int_{B(x_0, r)} |u|$$

For  $d=1$ , note that  $\partial_{x_i} u$  is also harmonic

$$\begin{aligned} \Rightarrow |\partial_{x_i} u(x_0)| &= \left| \int_{B(x_0, r/2)} \partial_{x_i} u(y) dy \right| \\ &= \left| \frac{1}{|B_1| \left(\frac{r}{2}\right)^d} \int_{B(x_0, r/2)} \partial_{x_i} u(y) dy \right| \\ &= \left| \frac{1}{|B_1| \left(\frac{r}{2}\right)^d} \int_{\partial B(x_0, r/2)} u \cdot n_i dS \right| \\ &\leq \frac{|S_1|}{|B_1| \left(\frac{r}{2}\right)^d} \|u\|_{L^\infty(\partial B(x_0, r/2))} \end{aligned}$$

and from the case  $d=0$

$$\|u\|_{L^\infty(\partial B(x_0, r/2))} \leq \frac{1}{|B_1| \left(\frac{r}{2}\right)^d} \int_{B(x_0, r)} |u|$$

More generally: if  $|2| = N$ , then

$$D^\alpha u = \partial_{x_i} (D^\beta u) \quad \text{with } |\beta| = N-1$$

$$\Rightarrow |D^\alpha u(x_0)| = \left| \int_{B(x_0, r/N)} \partial_{x_i} (D^\beta u) \right|$$

$$= \left| \frac{1}{|B_1| \left(\frac{r}{N}\right)^d} \left( \int_{\partial B(x_0, r/N)} D^\beta u \cdot n_i \, dS \right) \right|$$

$$\leq \frac{|S_1|}{|B_1| \left(\frac{r}{N}\right)^d} \|D^\beta u\|_{L^\infty(B(x_0, r/N))}$$

~~and by the induction hypothesis~~

~~$$\|D^\beta u\|_{L^\infty(B(x_0, \frac{r}{N}))} \leq \frac{[C_d(N-1)]^{N-1}}{r^{d+N-1}} \int_{B(x_0, r)} |u|$$~~

~~$$\Rightarrow |D^\alpha u(x_0)| \leq \frac{C_d N}{r} \cdot \frac{[C_d(N-1)]^{N-1}}{r^{d+N-1}} \int_{B(x_0, r)} |u|$$~~

~~$$\leq \frac{(C_d N)^N}{r^{N+d}} \int_{B(x_0, r)} |u| \quad \square$$~~

Note that if  $x \in B(x_0, \frac{r}{N})$ , then

$$B(x, r \frac{N-1}{N}) \subset B(x_0, r).$$

Hence, by the induction hypothesis

$$\|D^\beta u\|_{L^\infty(B(x_0, \frac{r}{N}))} \leq \sup_{x \in B(x_0, \frac{r}{N})} |D^\beta u(x)|$$

$$\leq \frac{[C_d(N-1)]^{N-1}}{[r \frac{N-1}{N}]^{d+N-1}} \int_{B(x_0, r)} |u|$$

$$= \frac{C_d^{N-1}}{[r \frac{N-1}{N}]^d} \cdot \frac{1}{(r/N)^{N-1}} \int_{B(x_0, r)} |u|$$

$$\leq \frac{2^d C_d^{N-1}}{r^d} \cdot \frac{1}{(r/N)^{N-1}} \int_{B(x_0, r)} |u|$$

$$\Rightarrow |D^\beta u(x_0)| \leq \frac{|S_1|}{|B_1| (r/N)} \cdot \|D^\beta u\|_{L^\infty(B(x_0, \frac{r}{N}))}$$

$$\leq \frac{2^d |S_1| \cdot C_d^{N-1}}{|B_1|} \cdot \frac{1}{r^d} \cdot \frac{1}{(r/N)^N} \int_{B(x_0, r)} |u|$$

$$\leq \frac{(C_d N)^N}{r^{d+N}} \int_{B(x_0, r)} |u|.$$

Theorem (Liouville's theorem) If  $u \in C^2(\mathbb{R}^d)$  is harmonic and bounded, then  $u = \text{const.}$

Proof:

$$\begin{aligned} |\Delta u(x_0)| &\leq \frac{C_d}{r^{d+1}} \int_{B(x_0, r)} |u| \\ &\leq \frac{C_d}{r} \rightarrow 0 \text{ as } r \rightarrow \infty \end{aligned}$$

Theorem (Uniqueness of Poisson eq. in  $\mathbb{R}^d$ )

Let  $f \in C_c^2(\mathbb{R}^d)$ ,  $d \geq 3$ . Then any bounded,  $C^2(\mathbb{R}^d)$  solution of Poisson eq.  $-\Delta u = f$  in  $\mathbb{R}^d$  is of the form

$$u(x) = \Phi * f + C = \int_{\mathbb{R}^d} \Phi(x-y) f(y) dy + C$$

Here  $C$  is a constant and  $\Phi$  the fundamental solution of Laplace equation in  $\mathbb{R}^d$ .

Proof:

$\Phi(x) \rightarrow 0$  as  $\infty \Rightarrow u$  is bounded

$\Rightarrow$  uniqueness. (In 2D,  $\Phi \rightarrow \infty$  as  $\infty$ )

## Exercise: (Harnack's inequality)

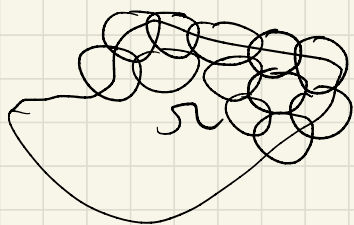
Let  $u \in C^2(\mathbb{R}^d)$  be harmonic and non-negative.

Prove that for every open, bounded, connected set  $\Omega \subset \mathbb{R}^d$  we have:

$$\sup_{x \in \Omega} u(x) \leq C_{\Omega} \inf_{x \in \Omega} u(x)$$

for a finite constant  $C_{\Omega}$  depending only on  $\Omega$ .

Hint: Consider first the case  $\Omega =$  a ball. In the general case,  $\Omega$  can be covered by a finite collection of balls & one of them is



contained completely inside  $\Omega$ . ◻

- So far we did not construct a solution of Poisson equation  $-\Delta u = f$  in  $\Omega$ . This can be done using Green function. But before doing so, let us discuss some basic facts of the convolution & Fourier transform.