

## Chapter 5: Heat equation

$$\begin{cases} \partial_t u = \Delta u & \text{in } \mathbb{R}^d \times (0, \infty) \\ u|_{t=0} = g & \text{(initial data)} \end{cases}$$

Fundamental solution:

$$\Phi(x, t) = \frac{1}{(4\pi t)^{d/2}} e^{-\frac{|x|^2}{4t}}, \quad x \in \mathbb{R}^d, t > 0$$

$$\begin{cases} \partial_t \Phi = \Delta \Phi & \text{in } \mathbb{R}^d \times (0, \infty) \\ \int_{\mathbb{R}^d} \Phi(x, t) dx = 1, \quad \forall t > 0 \\ \lim_{t \rightarrow 0} \Phi(x, t) = \delta_0(x) & \text{in } D'(\mathbb{R}^d). \end{cases}$$

Theorem: If  $g \in C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$ , then

$$u(x, t) = \int_{\mathbb{R}^d} \Phi(x-y, t) g(y) dy$$

satisfies (i)  $u \in C^\infty(\mathbb{R}^d \times (0, \infty))$

(ii)  $\partial_t u = \Delta u$ ,  $\forall (x, t) \in \mathbb{R}^d \times (0, \infty)$

(iii)  $\lim_{t \rightarrow 0} u(x, t) = g(x)$ ,  $\forall x \in \mathbb{R}^d$ .

Theorem: (Non homogeneous problem)

Let  $f \in C_1^2(\mathbb{R}^d, [0, \infty))$ , compact support.

Define  $u(x, t) = \int_0^t \int_{\mathbb{R}^d} \phi(x-y, t-s) f(y, s) dy ds$

Then: (i)  $u \in C_1^2(\mathbb{R}^d \times (0, \infty))$

(ii)  $\partial_t u = \Delta u + f$ ,  $\forall x \in \mathbb{R}^d, t > 0$

(iii)  $\lim_{t \rightarrow 0} u(x, t) = 0$ ,  $\forall x \in \mathbb{R}^d$ .

Proof: We write

$$u(x, t) = \int_0^t \int_{\mathbb{R}^d} \phi(y, s) f(x-y, t-s) dy ds$$

$$\rightarrow \partial_t u(x, t) = \int_0^t \int_{\mathbb{R}^d} \phi(y, s) \partial_t f(x-y, t-s) dy ds$$

$$+ \int_{\mathbb{R}^d} \phi(y, s) f(x-y, 0) dy$$

and  $\partial_{ij} u(x, t) = \int_0^t \int_{\mathbb{R}^d} \phi(y, s) \partial_{ij} f(x-y, t-s) dy$

$\Rightarrow \partial_t u, \partial_{ij} u$  (and  $u, \partial_i u$ ) are in  $C(\mathbb{R}^d \times (0, \infty))$

Next we calculate:

$$\begin{aligned}\partial_t u - \Delta u &= \int_0^t \int_{\mathbb{R}^d} \phi(y, s) (\partial_t - \Delta_x) f(x-y, t-s) dy ds \\ &\quad + \int_{\mathbb{R}^d} \phi(y, s) f(x-y, 0) dy \\ &= \int_{\varepsilon}^t \int_{\mathbb{R}^d} \dots + \int_0^{\varepsilon} \int_{\mathbb{R}^d} \dots + \int_{\mathbb{R}^d} \phi(y, s) f(x-y, 0) dy \\ &= I_{\varepsilon} + J_{\varepsilon} + K.\end{aligned}$$

$$\begin{aligned}\text{Here } |J_{\varepsilon}| &\leq \|(\partial_t - \Delta_x) f\|_{L^{\infty}} \int_0^{\varepsilon} \int_{\mathbb{R}^d} \phi(y, s) dy ds \\ &\leq C\varepsilon \rightarrow 0 \text{ as } \varepsilon \rightarrow 0\end{aligned}$$

$$\begin{aligned}\text{and } J_{\varepsilon} &= \int_{\varepsilon}^t \int_{\mathbb{R}^d} \phi(y, s) (-\partial_s - \Delta_y) f(x-y, t-s) dy ds \\ &= \int_{\varepsilon}^t \int_{\mathbb{R}^d} \underbrace{(\partial_s - \Delta_y) \phi(y, s)}_{=0} f(x-y, t-s) dy ds \\ &\quad - \int_{\mathbb{R}^d} \phi(y, s) f(x-y, t-s) \Big|_{s=\varepsilon}^{s=t} dy \\ &= \int_{\mathbb{R}^d} \phi(y, \varepsilon) f(x-y, t-\varepsilon) dy - K\end{aligned}$$

$$\Rightarrow I_{\varepsilon} + K = \int_{\mathbb{R}^d} \Phi(y, \varepsilon) f(x-y, t-\varepsilon) dy \xrightarrow{\varepsilon \rightarrow 0} f(x, t)$$

Thus

$$\partial_t u - \Delta u = f(x, t), \quad \forall (x, t) \in \mathbb{R}^d \times (0, \infty).$$

Finally:

$$\begin{aligned} \|u(\cdot, t)\|_{L^\infty} &\leq \|f\|_{L^\infty} \int_0^t \int_{\mathbb{R}^d} \Phi(y, s) dy ds \\ &= \|f\|_{L^\infty} t \rightarrow 0 \text{ as } t \rightarrow \infty. \end{aligned}$$

Remark: As  $f$  &  $g$  given as above,

$$u(x, t) = \int_{\mathbb{R}^d} \Phi(x-y, t) g(y) dy + \int_0^t \int_{\mathbb{R}^d} \Phi(x-y, t-s) f(y, s) ds$$

$$\text{solves } \begin{cases} \partial_t - \Delta u = f \\ u(t=0) = g. \end{cases}$$

(Exercise)

Remark: (Duhamel formula)

Consider the ODE:  $\partial_t w(t) = Aw(t)$ ,  $A \in \mathbb{R}$

$$\Rightarrow w(t) = e^{tA} w(0)$$

More generally:

$$\dot{y} \quad \partial_t w(t) = A w(t) + f(t)$$

$$\begin{aligned} \Rightarrow \partial_t \left( e^{-tA} w(t) \right) &= e^{-tA} \left( \partial_t w(t) - A w(t) \right) \\ &= e^{-tA} f(t) \end{aligned}$$

$$\Rightarrow e^{-tA} w(t) = w(0) + \int_0^t e^{-sA} f(s) ds$$

$$\Rightarrow w(t) = e^{tA} w(0) + \int_0^t e^{(t-s)A} f(s) ds$$

More generally, if  $A$  is an operator (independent of time) then:

$$\partial_t w(t) = A w(t) + f(t)$$

$$\Rightarrow w(t) = e^{tA} w(0) + \int_0^t e^{(t-s)A} f(s) ds.$$

Application: If  $A = \Delta$ , then the operator  $e^{t\Delta}$  has kernel

$$e^{t\Delta}(x, y) = \phi(x-y, t) = \frac{1}{(4\pi t)^{d/2}} e^{-\frac{|x-y|^2}{4t}}$$

$\leadsto$  called the heat kernel.

Theorem ( $L^2$ -data) For every  $g \in L^2(\mathbb{R}^d)$ , define

$$u(t, x) = \int_{\mathbb{R}^d} \Phi(x-y, t) g(y) dy.$$

Then  $u \in C^\infty(\mathbb{R}^d \times (0, \infty))$  and it solve the heat eq

$$\begin{cases} \partial_t u = \Delta_x u & \text{in } \mathbb{R}^d \times (0, \infty) \\ \lim_{t \rightarrow 0} u(\cdot, t) = g & \text{in } L^2(\mathbb{R}^d). \end{cases}$$

Proof: Recall the heuristic computation from the heat equation using the Fourier transform

$$\partial_t u(x, t) = \Delta_x u(x, t)$$

$$\Leftrightarrow \partial_t \hat{u}(k, t) = -|2\pi k|^2 \hat{u}(k, t)$$

$$\Leftrightarrow \partial_t \left( e^{t|2\pi k|^2} \hat{u}(k, t) \right) = 0$$

$$\Leftrightarrow e^{t|2\pi k|^2} \hat{u}(k, t) = \hat{u}(k, 0) = \hat{g}(k)$$

$$\Leftrightarrow \hat{u}(k, t) = e^{-t|2\pi k|^2} \hat{g}(k) = \hat{\Phi}(k, t) \hat{g}(k) = \widehat{\Phi * g}$$

$$\Leftrightarrow u(x, t) = \Phi * g = \int_{\mathbb{R}^d} \Phi(x-y, t) g(y) dy$$

Here we only need the direction " $\Leftarrow$ " which is rigorous if  $g \in L^2(\mathbb{R}^d)$ .

From the Fourier transform, it is also easy to check that  $u(\cdot, t) \rightarrow g$  in  $L^2$  as  $t \rightarrow 0$  (exercise)

To see the smoothness, note that  $\forall t > 0, \forall m \in \mathbb{N}$   
 $(1 + |2\pi k|^m) \hat{u}(k, t) = \underbrace{(1 + |2\pi k|^m)}_{\in L^\infty} e^{-t|2\pi k|^2} \underbrace{\hat{g}(k)}_{\in L^2} \in L^2$

$\Rightarrow u(\cdot, t) \in H^m(\mathbb{R}^d), \forall m \geq 1.$

$\Rightarrow u(\cdot, t) \in C^\infty(\mathbb{R}^d)$  by Sobolev embedding (see below). This argument can be also used to show that  $u \in C^\infty(\mathbb{R}^d \times (0, \infty))$  (exercise).

Theorem (Sobolev embedding) If  $m > d/2$ , then:  
 $H^m(\mathbb{R}^d) \subset (C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d))$

Proof, We write  $\forall u \in H^m(\mathbb{R}^d)$ :

$$\hat{u}(k) = \underbrace{\hat{u}(k)}_{\in L^2 \text{ as } u \in H^m} \underbrace{(1 + |2\pi k|^m)}_{\in L^2 \text{ as } m > \frac{d}{2}}$$

$\Rightarrow \hat{u}(k) \in L^1(\mathbb{R}^d)$

$\Rightarrow u = (\hat{u})^\vee \in (C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d))$ .

## Maximum principle:

Recall Poisson equation  $-\Delta u \leq 0$  in  $\Omega$  open, bounded

$$\Rightarrow \sup_{\bar{\Omega}} u(x) = \sup_{\partial\Omega} u(x)$$

Theorem: (Maximum principle for bounded sets)

Let  $\Omega \subset \mathbb{R}^d$  be open, bounded, let  $T > 0$  and define

$$\Omega_T = \Omega \times (0, T), \quad \partial^* \Omega_T = (\bar{\Omega} \times \{0\}) \cup (\partial\Omega \times [0, T])$$

If  $u \in C_1^2(\Omega_T) \cap C(\bar{\Omega}_T)$  solves

$$\partial_t u - \Delta_x u \leq 0 \text{ in } \Omega_T$$

then:

$$\max_{\bar{\Omega}_T} u = \max_{\partial^* \Omega_T} u.$$

Proof: We will use Hopf's argument which is simpler than the mean-value theorem (there exists a mean-value theorem for heat equation, but it is complicated and we will not discuss).

Proof for Poisson eq: Assume  $u \in C^2(\Omega) \cap C(\bar{\Omega})$

Step 1: Assume  $\Delta u > 0$  in  $\Omega$ . Since  $\bar{\Omega}$  is

compact,  $\exists x_0 \in \bar{\Omega}$  s.t.  $u(x_0) = \max_{x \in \bar{\Omega}} u(x)$ .



We prove that  $x_0 \in \partial\Omega$ . In fact, if  $x_0 \in \Omega$ , then since  $x_0$  is a (local) maximizer of  $u$  in  $\Omega$ , we have  $\Delta u(x_0) \leq 0$ , which contradicts to the assumption that  $\Delta u > 0$  in  $\Omega$ .

Thus  $x_0 \in \partial\Omega$ , and hence:

$$\max_{x \in \bar{\Omega}} u(x) = u(x_0) \in \max_{x \in \partial\Omega} u(x).$$

Step 2: Now assume  $\Delta u \geq 0$  in  $\Omega$ . Define:

$$u_\varepsilon(x) = u(x) + \varepsilon |x|^2, \quad \varepsilon > 0.$$

Then  $\Delta u_\varepsilon > 0$  in  $\Omega$ , hence by Step 1 and

$$u \leq u_\varepsilon \leq u + \varepsilon \sup_{x \in \bar{\Omega}} |x|^2$$

we have:

$$\max_{x \in \bar{\Omega}} u(x) \leq \max_{x \in \bar{\Omega}} u_\varepsilon(x) \leq \max_{x \in \partial\Omega} u_\varepsilon(x) \leq$$

$$\leq \max_{x \in \partial\Omega} u(x) + \varepsilon \left( \sup_{x \in \bar{\Omega}} |x|^2 \right) \xrightarrow{\varepsilon \rightarrow 0} \max_{x \in \partial\Omega} u(x).$$

Proof for heat equation:

Step 1 Assume  $u \in C^2_1(\Omega \times (0, T]) \cap C(\bar{\Omega} \times [0, T])$

and  $\partial_t u - \Delta_x u < 0$  in  $\Omega \times (0, T]$ .

Then  $\exists (x_0, t_0) \in \bar{\Omega} \times [0, T]$  s.t.

$$u(x_0, t_0) = \max_{(x, t) \in \bar{\Omega} \times [0, T]} u(x, t).$$

We prove that  $(x_0, t_0) \in \partial^* \Omega_T$ . Assume by contradiction that  $(x_0, t_0) \notin \partial^* \Omega_T$ , then

$$x_0 \in \Omega \text{ and } t_0 \in (0, T].$$

Since  $x \mapsto u(x, t_0)$  has a (local) maximizer

$$x_0 \in \Omega \Rightarrow \Delta_x u(x_0, t_0) \leq 0$$

Since  $t \mapsto u(x_0, t)$  has a (local) maximizer

$$t_0 \in (0, T] \Rightarrow \partial_t u(x_0, t_0) \geq 0$$

$$\text{Thus: } (\partial_t u - \Delta_x u)(x_0, t_0) \geq 0$$

which is a contradiction to the assumption.

$$\text{Thus: } (x_0, t_0) \in \partial^* \Omega_T, \text{ i.e. } \max_{\bar{\Omega}_T} u = \max_{\partial^* \Omega_T} u.$$

Step 2. Assume  $u \in C_1^2(\Omega \times (0, T)) \cap C(\bar{\Omega} \times [0, T])$

and  $\partial_t u - \Delta_x u \leq 0$  in  $\Omega \times (0, T)$ .

Let  $\tilde{T} \in (0, T)$  and for  $\varepsilon > 0$ ,

$$u_\varepsilon(x, t) = u(x, t) + \varepsilon |x|^2.$$

Then:  $u_\varepsilon \in C_1^2(\Omega \times (0, \tilde{T}]) \cap C(\bar{\Omega} \times [0, \tilde{T}])$

and  $\partial_t \tilde{u}_\varepsilon - \Delta_x \tilde{u}_\varepsilon < 0$  in  $\Omega \times (0, \tilde{T}]$ .

By Step 1:  $\max_{\bar{\Omega}_{\tilde{T}}} \tilde{u}_\varepsilon \leq \max_{\partial^* \Omega_{\tilde{T}}} \tilde{u}_\varepsilon$

$$\xrightarrow{\varepsilon \rightarrow 0} \max_{\bar{\Omega}_{\tilde{T}}} u \leq \max_{\partial^* \Omega_{\tilde{T}}} u$$

$$\xrightarrow{\tilde{T} \rightarrow T} \max_{\bar{\Omega}_T} u \leq \max_{\partial^* \Omega_T} u. \quad \square$$

Theorem (Maximum principle for  $\Omega = \mathbb{R}^d$ )

Let  $\Omega_T = \mathbb{R}^d \times (0, T)$ ,  $\bar{\Omega}_T = \mathbb{R}^d \times [0, T]$ .

Let  $u \in C^2(\Omega_T) \cap C(\bar{\Omega}_T)$  such that

- $\partial_t u - \Delta_x u \leq 0$  in  $\Omega_T$
- $u(x, t) \leq M e^{M|x|^2}$ ,  $\forall (x, t) \in \bar{\Omega}_T$ .

Then

$$\sup_{\bar{\Omega}_T} u(x, t) = \sup_{x \in \mathbb{R}^d} u(x, 0).$$

Proof: Step 1:  $\forall y \in \mathbb{R}^d$  and  $\varepsilon > 0$  define

$$v(x, t) = u(x, t) - \frac{\varepsilon}{(T + \varepsilon - t)^{d/2}} \exp\left(\frac{|x - y|^2}{4(T + \varepsilon - t)}\right)$$

$$\Rightarrow \partial_t v - \Delta_x v = \partial_t u - \Delta_x u \leq 0 \text{ in } \Omega_T$$

For  $U = B(y, r)$ ,  $U_T = U \times (0, T)$ ,  $\bar{U}_T = \bar{U} \times [0, T]$

$$\partial^* U_T = (U \times \{0\}) \cup (\partial U \times [0, T])$$

By the maximum principle for  $U$  bounded,

$$\max_{\bar{U}_T} v \leq \max_{\partial^* U_T} v$$

let us bound  $\max_{\partial^* U_T} v$ .

.) On  $U \times \{0\}$  we use  $v \leq u$ , and hence

$$\max_{x \in \bar{U}} v(x, 0) \leq \max_{x \in \bar{U}} u(x, 0) \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

.) On  $\partial U \times [0, T]$  we use:  $|x-y| = r \Rightarrow |x| \leq |y| + r$

$$\begin{aligned} v(x, t) &= u(x, t) - \frac{\varepsilon}{(T+\varepsilon-t)^{d/2}} \exp\left(-\frac{|x-y|^2}{4(T+\varepsilon-t)}\right) \\ &\leq M e^{M(|y|+r)^2} - \frac{\varepsilon}{(T+\varepsilon)^{d/2}} \exp\left(-\frac{r^2}{4(T+\varepsilon)}\right) \end{aligned}$$

$$\rightarrow -\infty \text{ as } r \rightarrow \infty \quad \text{if } M < \frac{1}{4(T+\varepsilon)}.$$

In particular, we can choose  $r$  large s.t.

$$\max_{\substack{x \in \partial U, \\ t \in [0, T]}} v(x, t) \leq \max_{x \in \mathbb{R}^d} u(x, 0).$$

In summary, if  $M < \frac{1}{4(T+\varepsilon)}$ , then:

$$v(y, t) \leq \max_{\bar{u}_+} v \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

$$u(y, t) - \frac{\varepsilon}{(T+\varepsilon-t)^{d/2}}$$

This holds for all  $(y, t) \in \mathbb{R}^d \times [0, T]$

$$\Rightarrow \max_{\mathbb{R}^d \times [0, T]} u \leq \frac{\varepsilon}{(T+\varepsilon-t)^{d/2}} + \max_{x \in \mathbb{R}^d} u(x, 0)$$

Taking  $\varepsilon \rightarrow 0$  we conclude that if  $M < \frac{1}{4T}$ ,

$$\max_{\mathbb{R}^d \times [0, T]} u \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

Step 2: For general  $T$ , we denote:

$$T_1 = \frac{T}{N}, \quad N \in \mathbb{N} \text{ s.t. } M < \frac{1}{4T_1}$$

Then by Step 1:

$$\max_{\mathbb{R}^d \times [0, T_1]} u \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

$$\max_{\mathbb{R}^d \times [T_1, 2T_1]} u \leq \max_{x \in \mathbb{R}^d} u(x, T_1) \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

$$\max_{\mathbb{R}^d \times [(N-1)T_1, NT_1]} u \leq \max_{x \in \mathbb{R}^d} u(x, (N-1)T_1) \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

$$\leadsto \max_{\mathbb{R}^d \times [0, T]} u \leq \max_{x \in \mathbb{R}^d} u(x, 0)$$

Remark: The condition  $u \leq M e^{M|x|^2}$  is necessary; otherwise,  $\exists$  solutions  $u \neq 0$  s.t.  $u(x, 0) = 0$ .

Theorem (Uniqueness)

$$\exists u \in C_1^2(\mathbb{R}^d \times (0, T)) \cap C(\mathbb{R}^d \times [0, T])$$

$$u(x, t) \leq M e^{M|x|^2} \text{ in } \mathbb{R}^d \times [0, T]$$

$$\partial_t u - \Delta_x u = 0 \text{ in } \mathbb{R}^d \times (0, T)$$

$$u(x, 0) = 0 \text{ in } \mathbb{R}^d$$

Then  $u = 0$  in  $\mathbb{R}^d \times [0, T]$ .

Proof: Use the maximum principle for  $u$  &  $-u$ .

Remark: If we know that  $u(\cdot, t) \in L^2(\mathbb{R}^d)$ , then the proof of the uniqueness is easier.

Heuristically:

$$\begin{aligned} \frac{d}{dt} \int_{\mathbb{R}^d} |u(x, t)|^2 dx &= 2 \int_{\mathbb{R}^d} \partial_t u \cdot u \, dx \\ &= 2 \int_{\mathbb{R}^d} \Delta_x u \cdot u \, dx = - \int_{\mathbb{R}^d} |\nabla_x u|^2 dx \leq 0 \end{aligned}$$

$\Rightarrow e(t) = \int_{\mathbb{R}^d} |u(x, t)|^2 dx$  is decreasing

Hence, if  $e(0) = 0 \Rightarrow e(t) = 0 \quad \forall t \geq 0$ .

This argument will be helpful below for the heat backward equation.

Remark: The heat equation 
$$\begin{cases} \partial_t u - \Delta_x u = 0 \\ u(t=0) = g \end{cases}$$

is a well-posed problem (unknown  $u(\cdot, t), t > 0$ )

• Existence

• Uniqueness

• Stability (solution depends continuously on data)



For the latter issue, by the maximum principle we have

$$\|u(\cdot, t)\|_{L^\infty} \leq \|u(\cdot, 0)\|_{L^\infty}, \forall t$$

or in the  $L^2$ -situation

$$\|u(\cdot, t)\|_{L^2} \leq \|u(\cdot, 0)\|_{L^2}, \forall t.$$

On the other hand, the heat back-ward equation

$$\begin{cases} \partial_t u - \Delta_x u = 0 \\ u(t=T) = g \end{cases} \quad \begin{array}{l} \text{(unknown} \\ u(\cdot, t), t < T) \end{array}$$

is not well-posed.

• Non-existence: in general, the existence require some special property on  $g$ , e.g.  $g$  is very smooth (only  $g \in C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$  or  $g \in L^2(\mathbb{R}^d)$  is not enough).

• Uniqueness: on the other hand, the uniqueness still holds.

Thm: If  $u \in C_1^2(\mathbb{R}^d \times [0, T]) \cap C^1(H^1(\mathbb{R}^d), [0, T])$

and

$$\begin{cases} \partial_t u - \Delta_x u = 0 & \text{in } \mathbb{R}^d \times (0, T) \\ u(x, T) = 0 \end{cases}$$

Then  $u = 0$  in  $\mathbb{R}^d \times [0, T]$ .

Proof: Recall  $e(t) = \int_{\mathbb{R}^d} |u(x, t)|^2 dx$  satisfies

$$e'(t) = 2 \int_{\mathbb{R}^d} u \cdot \partial_t u \, dx = 2 \int_{\mathbb{R}^d} u \Delta_x u \, dx = -2 \int_{\mathbb{R}^d} |\Delta_x u|^2 dx$$

Moreover,

$$\begin{aligned} e''(t) &= -4 \int_{\mathbb{R}^d} \nabla_x u \cdot \nabla_x (\partial_t u) \, dx = 4 \int_{\mathbb{R}^d} \Delta_x u \cdot \partial_t u \, dx \\ &= 4 \int_{\mathbb{R}^d} |\Delta_x u|^2 dx \geq 0 \end{aligned}$$

and hence

$$\begin{aligned} |e'(t)|^2 &= 4 \left| \int_{\mathbb{R}^d} u \Delta_x u \, dx \right|^2 \leq 4 \left( \int_{\mathbb{R}^d} |u|^2 dx \right) \left( \int_{\mathbb{R}^d} |\Delta_x u|^2 dx \right) \\ &= e(t) e''(t). \end{aligned}$$

Lemma: If  $e \in C^2(0, T)$ ,  $e(t) \geq 0$ ,  $e'(t) \leq 0$ ,

$e''(t) \geq 0$  and  $|e'(t)|^2 \leq e(t) e''(t)$  for  $t \in [0, T]$

and  $e(T) = 0$ , then  $e \equiv 0$ .

Proof: Since  $e \downarrow$  and  $e(T) = 0$ ,  $\exists t_0 \in (0, T]$  s.t.

$$e(t_0) = 0 \quad \text{and} \quad e(t) > 0 \quad \forall t \leq t_0.$$

We need to prove that  $t_0 = 0$ . If not,  $0 < t_0 \leq T$ , then define

$$f(t) = \log e(t), \quad t \in (0, t_0)$$

$$\Rightarrow f'(t) = \frac{e'(t)}{e(t)}$$

$$\Rightarrow f''(t) = \frac{e''(t)e(t) - |e'(t)|^2}{e(t)^2} \geq 0$$

$\Rightarrow f$  is convex

$$\Rightarrow f(\tau t_1 + (1-\tau)t_2) \leq \tau f(t_1) + (1-\tau)f(t_2)$$

$$\forall t_1, t_2 \in (0, t_0) \quad \text{and} \quad \tau \in (0, 1)$$

$$\Rightarrow e(\tau t_1 + (1-\tau)t_2) \leq e(t_1)^\tau e(t_2)^{1-\tau}$$

$$\forall t_1, t_2 \in (0, t_0) \quad \text{and} \quad \tau \in (0, 1).$$

$$\text{Taking } t_2 \rightarrow t_0 \Rightarrow e(\tau t_1 + (1-\tau)t_0) = 0$$

$$\text{Taking } \tau \rightarrow 1 \Rightarrow e(t_1) = 0, \quad \forall t_1 \in (0, t_0)$$

which is a contradiction.  $\square$

# Instability of the back-ward heat equation

Theorem (Instability) There exist functions  $u_\varepsilon \in C_1^2(\mathbb{R}^d \times (0, T)) \cap C^1(H^1(\mathbb{R}^d) \times [0, T])$  s.t.

$$\partial_t u - \Delta_x u = 0 \text{ in } \mathbb{R}^d \times (0, T)$$

such that when  $\varepsilon \rightarrow 0^+$

$$\|u_\varepsilon(\cdot, T)\|_{L^2(\mathbb{R}^d)} \rightarrow 0, \quad \|u_\varepsilon(\cdot, 0)\|_{L^2(\mathbb{R}^d)} \rightarrow \infty$$

Remark: This means that a small error of the data at  $t=T$  may cause a large error of the output  $t=0$ .

Proof: Recall by Fourier transform

$$\partial_t \hat{u}(k, t) = -|2\pi k|^2 \hat{u}(k, t)$$

$$\Rightarrow \hat{u}(k, t) = e^{-t|2\pi k|^2} \hat{u}(k, 0)$$

$$\Rightarrow \hat{u}(k, 0) = e^{T|2\pi k|^2} \hat{u}(k, T)$$

We can take  $\hat{u}_\varepsilon(k, T) = \mathbb{1}_{(|k| \leq \varepsilon^{-1})} \varepsilon^{\frac{d+1}{2}}$

$$\Rightarrow \|u_\varepsilon(\cdot, T)\|_{L^2(\mathbb{R}^d)}^2 = \int_{\mathbb{R}^d} \mathbb{1}_{(|k| \leq \varepsilon^{-1})} \varepsilon^{d+1} dk$$

$$\sim \varepsilon \rightarrow 0$$

and

$$\|u_\varepsilon(\cdot, 0)\|_{L^2(\mathbb{R}^d)}^2 = \int_{\mathbb{R}^d} e^{2T|\lambda|^2} \mathbb{1}_{(|\lambda| \leq \varepsilon^{-1})} \varepsilon^{d+1} d\lambda$$

$$\geq \int_{\frac{\varepsilon^{-1}}{2} \leq |\lambda| \leq \varepsilon^{-1}} \dots \geq e^{2T\varepsilon^{-2}} \varepsilon \rightarrow \infty \text{ as } \varepsilon \rightarrow 0$$

Theorem (Regularized solution) Assume that

$$u \in C^2_1(\mathbb{R}^d \times (0, T)) \cap C^1(H^1(\mathbb{R}^d), [0, T])$$

$$\begin{cases} \partial_t u - \Delta_x u = 0 & \text{in } \mathbb{R}^d \times (0, T) \\ u(x, T) = g(x) & \text{in } \mathbb{R}^d \end{cases}$$

Then from given data  $g_\varepsilon \in L^2(\mathbb{R}^d)$  s.t.

$$\|g_\varepsilon - g\|_{L^2(\mathbb{R}^d)} \leq \varepsilon$$

we can construct a sol  $\tilde{u}_\varepsilon$  s.t.

$$\sup_{t \in [0, T]} \|\tilde{u}_\varepsilon(\cdot, t) - u(\cdot, t)\|_{L^2(\mathbb{R}^d)} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0$$

Remark: For applications, both  $u$  and  $g$  are unknown, only  $g_\varepsilon$  is given. So we have to construct  $\tilde{u}_\varepsilon$  using only information from  $g_\varepsilon$ .

Proof: Clearly we should not choose  $\tilde{u}_\varepsilon$  to solve the eq  $\left\{ \begin{array}{l} \partial_t u_\varepsilon - \Delta_x u_\varepsilon = 0 \\ u_\varepsilon(t=T) = g_\varepsilon \end{array} \right.$

i.e.  $\hat{u}_\varepsilon(k, t) = e^{(\tau-t)(2\pi|k|^\nu)} \hat{g}_\varepsilon(k)$

Rather we take

$$\hat{\tilde{u}}_\varepsilon(k, t) = e^{(\tau-t)(2\pi|k|^\nu)} \hat{g}_\varepsilon(k) \mathbb{1}(|k| \leq \delta_\varepsilon^{-1})$$

where  $\delta_\varepsilon \rightarrow 0$  (chosen later).

Then we have for all  $t \in [0, T]$

$$\| \tilde{u}_\varepsilon(\cdot, t) - u(\cdot, t) \|_{L^2(\mathbb{R}^d)}^2 \quad g = u(\cdot, T)$$

$$= \int_{\mathbb{R}^d} e^{2(\tau-t)(2\pi|k|^\nu)} \left| \hat{g}_\varepsilon(k) \mathbb{1}(|k| \leq \delta_\varepsilon^{-1}) - \hat{g}(k) \right|^2 dk$$

$$\leq 2 \int_{\mathbb{R}^d} e^{2\tau(2\pi|k|^\nu)} \left| \hat{g}_\varepsilon(k) - \hat{g}(k) \right| \mathbb{1}(|k| \leq \delta_\varepsilon^{-1}) dk$$

$$+ 2 \int_{\mathbb{R}^d} e^{2\tau(2\pi|k|^\nu)} \underbrace{|\hat{g}(k)|^2}_{|\hat{u}(k, 0)|^\nu} \mathbb{1}(|k| > \delta_\varepsilon^{-1}) dk$$

$$= \text{(I)} + \text{(II)}$$

We have:

$$\begin{aligned} \text{(I)} &\leq 2 \int_{\mathbb{R}^d} e^{c\delta_\varepsilon^{-2}} |\hat{g}_\varepsilon(k) - \hat{g}(k)|^2 dk \\ &= 2 e^{c\delta_\varepsilon^{-2}} \varepsilon^{-2} \rightarrow 0 \quad \text{y} \quad \delta_\varepsilon \gg \frac{1}{\sqrt{\ln \varepsilon}} \end{aligned}$$

$$\begin{aligned} \text{(II)} &= 2 \int_{\mathbb{R}^d} |\hat{u}(k, 0)|^2 \mathbb{1}(|k| \geq \delta_\varepsilon^{-1}) dk \\ &\leq 2 \int_{\mathbb{R}^d} |k|^2 \delta_\varepsilon^2 |\hat{u}(k, 0)|^2 dk \\ &\leq 2 \delta_\varepsilon^2 \|u(\cdot, 0)\|_{H^1(\mathbb{R}^d)}^2 \rightarrow 0 \text{ as } \delta_\varepsilon \rightarrow 0. \end{aligned}$$

Thus choosing  $\frac{1}{\sqrt{\ln \varepsilon}} \ll \delta_\varepsilon \ll 1$ , e.g.

$\delta_\varepsilon = (\ln \varepsilon)^{-1/4}$  we find that

$$\sup_{t \in [0, T]} \|u_\varepsilon(\cdot, t) - u(\cdot, t)\|_{L^2(\mathbb{R}^d)} \leq \text{(I)} + \text{(II)} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0.$$

□