Smoothed Particle Hydrodynamics

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Smoothed Particle Hydrodynamics

- numerical method to simulate fluids (liquids, gases, plasmas)
- idea: represent fluid by moving particles
- first used in astrophysics
- increasingly used in CGI for block-buster movies
- upcoming technology for next-generation computer games

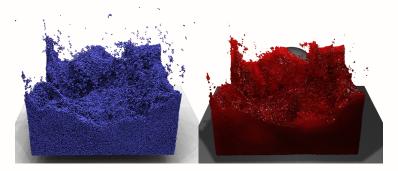


Figure : 1 Million particles, rendered in Maya, by Frank Zimmer

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ρ: ℝ^d → ℝ mass-density of the fluid

 A: ℝ^d → ℝ some charge-density the fluid (pressure, etc.):

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- Solution Want to approximate A by particles at positions r_k, k ∈ {1,...,N}.

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 k ∈ {1,...,N}.
- Note that $A(r) = (A * \delta)(r) = \int A(r')\delta(r r')dr'$
- Solution Approximate $\delta(r r')$ by $W_h(|r r'|)$, where
 - $\int W_h(|r-r'|) \mathrm{d}r' = 1$
 - $W_h \stackrel{*}{\rightharpoonup} \delta$ for $h \to 0$
 - $W_h \in C_0^\infty$
 - supp $W_h \subset [0, \kappa h]$, $\kappa > 0$

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- Interpolated field:

$$A_{I}(r) := \int A(r') W_{h}(|r-r'|) \mathrm{d}r' \approx A(r)$$

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• Observe that in

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only the kernel depends on position r.

Spatial derivatives

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• Gradient:

$$(\nabla A_S)(r) = \sum_{j=1}^N m_j \frac{A_j}{\rho_j} (\nabla W_h)(|r-r_j|) \frac{r-r_j}{|r-r_j|}$$

• Laplacian:

$$(\Delta A_{\mathcal{S}})(r) = \sum_{j=1}^{N} m_j \frac{A_j}{\rho_j} (\Delta W_h)(|r-r_j|)$$

Spatial derivatives

• SPH Field approximation

$$A_i = \sum_{j=1}^N m_j \frac{A_j}{\rho_j} W_h(|r_i - r_j|)$$

• SPH Gradient approximation:

$$(\nabla A)_i = \sum_{j=1}^N m_j \frac{A_j}{\rho_j} (\nabla W_h) (|r_i - r_j|) \frac{r_i - r_j}{|r_i - r_j|}$$

• SPH Laplacian approximation:

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Practical considerations

• Smoothing length *h* proportional to average particle diameter:

$$h \sim \frac{1}{\langle \rho \rangle^{\frac{1}{d}}}$$
, where $\langle \rho \rangle := \frac{1}{n} \sum_{i=1}^{N} \rho_i$

- Different kernels suitable for different charge densities.
- Kernels not C^{∞} due to performance considerations (Splines!).
- Golden rules of SPH (Monaghan):
 - To find physical interpretation it's always best to assume kernel is Gaussian.
 - Rewrite formulas with mass density inside operators, by making use of

$$abla A = rac{
abla (A\psi)}{\psi} - rac{A(
abla \psi)}{\psi}$$

for positive smooth ψ .

$$ho\left(\partial_t \mathbf{v} + \mathbf{v}\cdot
abla \mathbf{v}
ight) =
ho g -
abla p + \mu \Delta \mathbf{v}$$
, where

- v velocity
- g gravity
- p pressure
- μ viscosity

$$\rho\left(\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}\right) = \rho g - \nabla p + \mu \Delta \mathbf{v}$$

• Mass continuity equation:

$$ho\left(
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Mass continuity equation:

$$\rho\left(\nabla\cdot\mathbf{v}\right)=\mathbf{0}$$

will be trivially satisfied: each particle has constant mass and particles are neither created nor destroyed.

$$\rho\left(\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}\right) = \rho g - \nabla p + \mu \Delta \mathbf{v}$$

• Consider the total derivate of v(r, t) with respect to time:

$$\frac{\mathrm{d}}{\mathrm{d}t}v(r,t) = (\partial_t v)(r,t) + [\dot{r}(t)] \cdot (\nabla v)(r,t)$$

It depends on \dot{r} , where r(t) is a *chosen* path in space.

Equations of motion

• Navier-Stokes equation:

$$\rho\left(\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla \mathbf{v}\right) = \rho \mathbf{g} - \nabla \mathbf{p} + \mu \Delta \mathbf{v}$$

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It depends on \dot{r} , where r(t) is a *chosen* path in space.

• Velocity v_i of particle moving with the fluid, i.e. $\dot{r}_i = v_i$:

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathbf{v}_i = \partial_t \mathbf{v}_i + \mathbf{v}_i \cdot \nabla \mathbf{v}_i,$$

i.e. Navier-Stokes is just Newton's second law in disguise.

$$\rho \frac{\mathrm{d}}{\mathrm{d}t} \mathbf{v} = \rho \mathbf{g} - \nabla \mathbf{p} + \mu \Delta \mathbf{v}$$

• SPH approximation:

$$\rho_i \frac{\mathrm{d}}{\mathrm{d}t} \mathbf{v}_i = \rho_i \mathbf{g} - (\nabla \mathbf{p})_i + \mu (\Delta \mathbf{v})_i$$

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathbf{v} = \mathbf{g} - \frac{1}{\rho}\nabla \mathbf{p} + \frac{\mu}{\rho}\Delta \mathbf{v}$$

• SPH approximation:

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• $\frac{1}{\rho_i}(\nabla p)_i = \sum_{j=1}^N m_j \left(\frac{p_i}{\rho_i^2} + \frac{p_j}{\rho_j^2}\right) (\nabla W_h)(|\mathbf{r}_i - \mathbf{r}_j|) \frac{r_i - r_j}{|\mathbf{r}_i - \mathbf{r}_j|}$

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$$\frac{\mathrm{d}}{\mathrm{d}t}\mathbf{v}_{i} = \mathbf{g} - \frac{1}{\rho_{i}}(\nabla p)_{i} + \frac{\mu}{\rho_{i}}(\Delta \mathbf{v})_{i}$$

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•
$$\frac{\mu}{\rho_i}(\Delta v)_i = \frac{\mu}{\rho_i} \sum_{j=1}^N m_j \frac{v_j - v_i}{\rho_j} (\Delta W_h)(|r_i - r_j|)$$

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Still need to compute pressure!

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• Ideal gas law:

$$p = k_B \frac{N}{V} T$$
, where

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- N number of molecules
- V volume
- T (absolute) temperature
- *k*_B Boltzmann constant

• Ideal gas law:

$$p = k_B \frac{N}{V} T$$

Modelled as

$$p_i = k(\rho_i - \rho_{eq})$$
, where

- k constant depending on temperature
- ρ_{eq} equilibrium density (set to zero for ideal gas)

• Modelling of boundary conditions is an active area of research in SPH: the support of the kernel overlapping with boundaries leads to all sorts of problems.

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- Different types of boundaries:
 - Noslip-condition solid boundaries
 - Slip-condition solid boundaries
 - Mixtures of Slip/Noslip
 - Pressure boundaries
 - Flux boundaries
 - Reflective boundaries

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 - Ghost particles
 - Virtual forces
 - Analytical methods

Boundary conditions

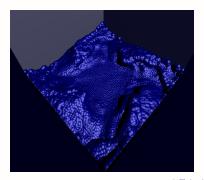
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- In my implementation: Noslip solid boundaries using ghost particles.

Active areas of research in SPH include:

- Boundary modelling
- Adaptivity
- Surface tension
- Solid adhesion

Demo

- 64k particles, interactive frame-rates
- Graphics running against DirectX 11 (Windows only)
- Simulation running against OpenCL (Windows, Linux, Android, Supercomputers...)
- Surface tension and solid adhesion modelled according to Akinci, Akinci and Teschner (2013), Freiburg



Please do not hesitate to ask questions!

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